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## **DERIVATIONS ON LIE IDEALS OF †1-PRIME X-RINGS**

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#### ABSTRACT

The authors extend and generalize some results of previous workers to  $\dagger 1$ -prime  $\Gamma$ -ring. For a  $\dagger 1$ -square closed Lie ideal U of a 2-torsion free  $\dagger 1$ -prime  $\Gamma$ -ring M, let  $d: M \to M$  be an additive mapping satisfying d(uX1u) = d(u)X1u + uX1d(u) for all  $u \in U$  and  $X1 \in \Gamma$ . The present authors proved that d(uX1v) = d(u)X1v + uX1d(v) for all  $u, v \in U$  and  $X1 \in \Gamma$ , and consequently, every Jordan derivation of a 2-torsion free  $\dagger 1$ -prime  $\Gamma$ -ring M is a derivation of M.

Key words: Lie ideal, †1-square closed Lie ideal, †1-prime Γ-ring, Derivation

#### INTRODUCTION

Oukhtite and Salhi (2008) worked on left derivations of <sup>†1</sup>-prime rings and proved that, if U is a nonzero  $\sigma$ 1-square closed Lie ideal of a ring R then  $U \subset Z(R)$ , centre of R or d(U) = 0. They described additive mappings  $d: R \to R$  such that  $d(u^2) = 2u d(u) \forall u \in U$ U, where U is a nonzero  $\dagger$ 1-square closed Lie ideal of a 2-torsion free  $\sigma$ 1-prime ring R and proved that  $d(uv) = ud(v) + vd(u) \quad \forall u, v \in U$ . Oukhtite *et al.* (2007) also studied Jordan generalized derivations of †1-prime rings and proved that every Jordan generalized derivations on U of R is a generalized derivations on U of R, where U is a  $\sigma$ 1-square closed Lie ideal of a 2-torsion free  $\uparrow$ 1-prime ring *R*. Some significant results developed on Lie ideals and generalized derivations in †1-prime rings by Khan and Khan (2012). Some characterizations of centralizing automorphisms on a †1-square closed Lie ideals of †1prime  $\Gamma$ -rings have been developed by Dey *et al.* (2015). They studied Jordan left derivations on a  $\sigma$ 1-square closed Lie ideals and proved that such type of Jordan derivations is a derivation on a  $\uparrow$ 1-square closed Lie ideals of a  $\uparrow$ 1-prime  $\Gamma$ -ring. Paul and Chakraborty (2015) studied  $\dagger$ 1-prime  $\Gamma$ -rings and proved that if a derivation d acting as homomorphism and an anti-homomorphism in a  $\sigma$ 1-Lie ideal U of a  $\sigma$ 1-prime  $\Gamma$ -ring M, then d = 0 or  $U \subseteq Z(M)$ . An example of an involution and an example of a  $\dagger 1$ -prime  $\Gamma$ ring which is not a prime  $\Gamma$ -ring appeared in Dey and Paul (2015). On the other hand, various remarkable characterizations of  $\uparrow$ 1-prime rings on  $\sigma$ 1-square closed Lie ideals have been studied by many authors viz. Bergun (1981), Herstein (1969), Khan et al. (2010), Oukhtite and Salhi (2006), Paul and Rahman (2015).

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The authors proved that if  $d: M \to M$  is an additive mapping satisfying d(uxlu) = d(u)xlu + uxld(u) for all  $u \in U$  and  $xl \in \Gamma$  then d(uxlv) = d(u)xlv + uxld(v) for all  $u, v \in U$  and  $xl \in \Gamma$ , where U is a  $\dagger 1$ -square closed Lie ideal of a 2-torsion free  $\dagger 1$ -prime  $\Gamma$ -ring M, and hence every Jordan derivations on a  $\dagger 1$ -prime  $\Gamma$ -ring M is a derivation on M.

Throughout this paper, the authors consider *M* an associative  $\Gamma$ -ring with centre Z(M). Define  $[x, y]_{x1} = xxly - yxlx$  which is known as the commutator of *x* and *y* with respect to xl. The authors assume the condition (\*)  $x \Gamma ySz = xSy\Gamma z \forall x, y, z \in M$  and  $\Gamma S \in \Gamma$ . Using this condition the basic commutator identities become  $[xSy, xz]_{x1} = [x, z]_{x1}Sy + xS[y, z]_{x1}$  and  $[x, ySz]_{x1} = [x, y]_{x1}Sz + yS[x, z]_{x1}$  for all  $x, y, z \in M$  and  $S, xl \in \Gamma$ . An additive subgroup *U* of a  $\Gamma$ -ring *M* is called a Lie ideal if  $[U, M]_{\Gamma} \subseteq U$ . An additive mapping  $d : M \to M$  is called a derivation if  $d(axlb) = d(a)xlb + axld(b)\forall xl, b \in M, xl \in \Gamma$  and *d* is a Jordan derivation but the converse is not true in general. A  $\Gamma$ -ring *M* is prime if  $a\Gamma M\Gamma b = 0$  implies that a = 0 or b = 0 for every *a*,  $b \in M$ . An additive mapping  $f : M \to M$  is called a generalized derivation with the associated derivation  $d : M \to M$  if  $f(axlb) = f(a)xla + axld(a)\forall a \in M, xl \in \Gamma$ , and it is called a Jordan generalized derivation with the associated derivation  $d \circ M$  of M if f(axla) = f(a)xlb + axld(b) for all  $a, b \in M$ ,  $xl \in \Gamma$ .

### DERIVATIONS ON LIE IDEALS OF †1-PRIME Γ-RINGS

Let *M* be a  $\Gamma$ -ring. A mapping  $\uparrow 1: M \to M$  is called an involution if  $\sigma 1(a + b) = \uparrow 1(a) + \sigma 1(b), \sigma 1^2(a) = a$  and  $\sigma (a \times b) = \sigma (b) \times \sigma 1(a)$  for all  $a, b \in M$  and  $\times 1 \in \Gamma$ . A Lie ideal *U* of a  $\Gamma$ -ring *M* is called a  $\sigma 1$ -Lie ideal if  $\sigma 1(U) = U$  and it is called a  $\sigma 1$ -square closed Lie ideal if it is a  $\uparrow 1$ -Lie ideal and for all  $u \in U \times 1 \in \Gamma$ ,  $u \times u \in U$ . A  $\Gamma$ -ring *M* with involution  $\sigma 1$  is said to be a  $\sigma 1$ -prime  $\Gamma$ -ring if  $a\Gamma M\Gamma b = a\Gamma M\Gamma \uparrow 1 = \{0\}$  implies that a = 0 or b = 0. It is worthwhile to note that every prime  $\Gamma$ -ring having an involution  $\uparrow 1$  is  $\uparrow 1$ -prime but the converse is not true in general. We define the set  $S_{a\uparrow 1}(M) = \{x = M : \sigma(x) = \pm x\}$  which is known as the set of symmetric and skew symmetric elements of *M*. Let *U* be a Lie ideal of a  $\Gamma$ -ring *M*. The present authors define centralizer of *U* with respect to *M* by  $C_M(U) = \{m \in M : m \times u = u \times m \forall u \in U, \times 1 \in \Gamma\}$ .

**Lemma 2.1.** [(Rahman and Paul 2013), Lemma 2.5] Let M be a  $\Gamma$ -ring and U be a Lie ideal of M such that  $u \Gamma u \in U$  for all  $u \in U$  and  $\Gamma \in \Gamma$ . If d is a Jordan derivation on U of M, then for all  $a, b, c \in U$  and  $\Gamma, S \in \Gamma$ , the following statements hold:

- (i) d(arb + bra) = d(a)rb + d(b)ra + ard(b) + brd(a)
- (ii) d(arbsa + asbra) = d(a)rbsa + d(a)sbra + ard(b)sa + asd(b)ar + arbsd(a) + asbsa(a)

In particular, if M is 2-torsion free and satisfies the condition (\*), then

- (*iii*) d(arbsa) = d(a)rbsa + ard(b)sa + arbsd(a)
- (iv) d(arbsc + crbsa) = d(a)rbsc + d(c)rsa + ard(b)sc + crd(b)sa + arbsd(c)+ crbsb(a)

**Lemma 2.2.** [(Rahman and Paul 2013), Lemma 2.8] Let *M* be a 2-torsion free  $\Gamma$ ring satisfying the condition (\*) and *U* be a Lie ideal of *M*. If *d* is a Jordan derivation on *U* of *M* then for all  $u, v, w \in U$  and  $\Gamma, S, X \in \Gamma$ , { $\Gamma(u, v)SwX$ ]  $[u, v]_{\Gamma} + [u, v]_{\Gamma} SwX$ ]{ $_{\Gamma}(u, v) = 0$ .

**Lemma 2.3.** [(Rahman and Paul 2013), Lemma 2.11] Let *M* be a 2-torsion free prime  $\Gamma$ -ring and *U* be an admissible Lie ideal of *M*. If  $a, b \in M$  or  $a \in M, b \in U$  such that a rxsb + b rxsa = 0 for all  $x \in U$  and  $r, s \in \Gamma$  then a rxsb + b rxsa = 0.

**Lemma 2.4.** Let *M* be a 2-torsion free  $\sigma$ 1-prime  $\Gamma$ -ring and *U* be a  $\sigma$ 1-Lie ideal of *M*. Let  $u \ge U$  such that  $[u, [u, x]_r]_r = 0$  for all  $x \in M$  and  $\Gamma \in \Gamma$ , then  $[u, x]_r = 0$ .

**Proof.** Since  $[u, [u, x]_r]_r = 0$  for all  $x \in M$  and  $r \in \Gamma$ . Let  $y \in M$  and  $x \in \Gamma$  be arbitrary elements.

Replacing x by xX y, we obtain

$$0 = [u, [u, xXy_{r}]_{r}$$
  
=  $[u, xX[u, y]_{r} + [u, x]_{r}Xy]_{r}$   
=  $[u, xX[u, y]_{r}]_{r} + [u, [u, x]_{r}Xy]_{r}$   
=  $xX[u, [u, y]_{r}]_{r} + [u, x]_{r}X[u, y]_{r} + [u, [u, x]_{r}]_{r}Xy + [u, x]_{r}X[u, y]_{r}$   
=  $2[u, x]_{r}X[u, y]_{r}$ .

Since *M* is 2-torsion free, so  $[u, x]_r \times [u, y]_r = 0$ . For every  $z \in M$  we have  $z \times x \in M$ . Putting  $z \times 1x$  for *y*, we have  $[u, x]_r \times [u, z \times x]_r = 0$ . Therefore,

> $0 = [u, x]_{r} X (zX[u, x]_{r} + [u, z]_{r} Xx)$ =  $[u, x]_{r} XzX[u, x]_{r} + [u, x]_{r} X[u, z]_{r} Xx$ =  $[u, x]_{r} XzX[u, x]_{r}$ .

Therefore,  $[u, x]_{\alpha} \gamma M \gamma [u, x]_{\alpha} = 0$ . Since  $\sigma (U) = U$ , we have  $\sigma (u) = u$ , for all  $u \in U$ .

Let  $x \in S_{a^{\dagger 1}}(M)$ . Then  $\sigma(x) = \pm x$ . If  $\sigma(u) = u$  and  $\sigma(x) = -x$ , then

$$+ ([u, x]_{r}) = + (urx - xru) = + (urx) - + (xru)$$
$$= + (x)r + (u) - + (u)r + (x) = -xru + urx = [u, x]_{r}$$

Hence  $[u, x]_r \times M \times [u, x]_r = [u, x]_r \times M \times \dagger ([u, x]_r) = 0$ . By the  $\sigma$ -primeness of M,  $[u, x]_r = 0$ .

**Lemma 2.5.** Let *M* be a 2-torsion free  $\sigma$ 1-prime  $\Gamma$ -ring and *U* be a nonzero  $\sigma$  -Lie ideal and a  $\uparrow$ 1-sub  $\Gamma$ -ring of *M*. Then either  $U \subseteq Z(M)$  or *U* contains a nonzero  $\sigma$  -ideal of *M*.

**Proof.** First let it be assumed that, U as a  $\dagger 1 - \Gamma$ -ring which is not commutative. Then for some  $u, v \in U$ ,  $[u, v]_{\Gamma} \neq 0$  and  $[u, v]_{\Gamma} \in U$ . Therefore, the ideal *S* of *M* generated by  $[u, v]_{\Gamma}$  is nonzero,  $S \subseteq U$  and  $\dagger 1(S) = S$ . On the other hand, let it be assumed that *U* is commutative. Then for every  $u \in U$   $[u, [u, x]_{\Gamma}]_{\Gamma} = 0$  for all  $x \in M$  and  $\Gamma \in \Gamma$ . Hence by Lemma 2.4,  $[u, x]_{\Gamma} = 0$  for all  $x \in M$  and  $\Gamma \in \Gamma$ . This shows that  $U \subseteq Z(M)$ .

**Lemma 2.6** If  $U \not\subseteq Z(M)$  is a †1-Lie ideal of a †1-prime  $\Gamma$ -ring M, then  $C_M(U) \subseteq Z(M)$ .

**Proof.**  $C_M(U)$  is both a †1-sub  $\Gamma$ -ring and a †1-Lie ideal of M and  $C_M(U)$  contains no nonzero †1-ideal of M. In view of Lemma 2.5,  $C_M(U) \subseteq Z(M)$ . Therefore,  $C_M(U) = Z(M)$ .

**Lemma 2.7.** Let U be a †1-Lie ideal of a †1-prime  $\Gamma$ -ring M and  $a \in M$ . If  $[\Gamma, [U, U]_{\Gamma}]_{\Gamma} = 0$  then  $[U, U]_{\Gamma} = 0$ , that is,  $C_M([U, U]) = C_M(U)$ .

**Proof.** If  $[U, U]_{\Gamma} \not\subseteq Z(M)$ , then by Lemma 2.6,  $\Gamma \in Z(M)$ , so *a* centralizes *U*.

On the contrary, let  $[U, U]_{\Gamma} \subseteq Z(M)$ , then  $[u, [u, x]_{x1}]_{x1} = 0 \quad \forall u \in U, x \in M \text{ and } x1 \in \Gamma$ .

In view of Lemma 2.4,  $[u, x]_{x1} = 0$ . This yields that  $U \subseteq Z(M)$ . For both the cases  $\Gamma \in C_M(U)$ .

This gives that  $C_M([U, U] = C_M(U)$ .

**Lemma 2.8.** Let  $U \not\subseteq Z(M)$  be a  $\dagger 1$ -square closed Lie ideal of a 2-torsion free  $\dagger 1$ -prime  $\Gamma$ -ring M and  $d: M \to M$  be an additive mapping satisfying d(ux|u) = d(u) x|u + ux|d(u) for all  $u \in U$  and  $x \in \Gamma$ . If  $\{ \Gamma(u, v) = d(ux|v) - d(u)x|v - ux|d(v)$  for all  $u, v \in U$  and  $\in \Gamma$ , then  $\{ \Gamma(u, v)|x||w|| = 0 \text{ for all } w \in U.$ 

**Proof.** Since  $U \not\subseteq Z(M)$  is a †1-square closed Lie ideal of a 2-torsion free †1-prime  $\Gamma$ -ring M and  $d: M \to M$  is an additive mapping satisfying d(uX|u) = d(u)X|u + uX|d(u) for all  $u \in U$  and  $X|1 \in \Gamma$ . So by Lemma 2.2,  $\{r(u, v)X|wX||[u, v]_{X|1} + [u, v]X|wX|\{r(u, v) = 0 \text{ for all } u, v, w \in U \text{ and } \Gamma, X \in \Gamma$ . (1)

Applying Lemma 2.3, for every  $w \in U$ , (1) implies that  $\{ r(u, v) \times |w| = 0. \}$ 

**Lemma 2.9.** Let U be a  $\dagger 1$ -square closed Lie ideal of a 2-torsion free  $\dagger 1$ -prime  $\Gamma$ -ring M and  $a, b \in M$  such that  $\Gamma SUX1b = \Gamma SUX1\dagger 1$  (b) = 0, then a = 0 or b = 0.

**Proof.** Suppose U contains an element  $u_0$  in  $S_{a\dagger 1}(M)$  such that  $M \le u_0 \in U$ . Let  $r \neq 0$ , there are two several cases. First consider  $u_0 \in Z(M)$ . If  $m \in M$  and  $a rm s u_0 x l b$ 

$$= armsu_0x_1^{\dagger}(b) = 0$$
 then  $armsu_0x_1b = armsu_0x_1^{\dagger}(b) = arms(u_0x_1b) = 0$ 

 $\Rightarrow u_0 \mathbf{X} \mathbf{1} b = 0.$ 

Since  $u_0 \in Z(M)$ , then  $u_0 \le M \ge 1$  =  $1(u_0) \le M \ge 0 \implies b = 0$ .

Next, consider  $u_0 \in Z(M)$ . Suppose  $a \upharpoonright [t, u_0] X = 0 \forall t \in M$ , then  $a \upharpoonright [t \otimes m, u_0] X = a \upharpoonright t \otimes [m, u_0] X = 0$ .

So  $a \cap M$ s  $[m, u_0]$ x $1 = 0 = a \cap M$ s  $([m, u_0]$ x $1) \Rightarrow [m, u_0]$ x $1 = 0 \forall m \in M$  which contradicts the assumption  $u_0 \in Z(M)$ .

Thus there exists  $t \in M$  such that  $a \cap [t, u_0] \times 1 \neq 0$ .

From  $ar[t, u_0] \times ImSb = ar[t, u_0] \times ImS^{\dagger 1}(b) = 0$  it follows that  $ar[t, u_0] \times ImSb = ar[t, u_0] \times ImS^{\dagger 1}(b) = 0$  and by the  $\dagger 1$ -primeness of M, b = 0.

Similarly, if  $b \neq 0$  then a = 0.

**Theorem 2.10.** Let *U* be a †1-square closed Lie ideal of a 2-torsion free †1-prime  $\Gamma$ ring *M* and  $d: M \to M$  be an additive mapping satisfying d(uX|u) = d(u)X|u + uX|d(u) for all  $u \in U$  and  $x1 \in \Gamma$  then d(uX|v) = d(u)X|v + uX|d(v) for all  $u, v \in U$  and  $x1 \in \Gamma$ .

**Proof.** If *U* is a non-commutative Lie ideal of *M*, then  $U \neq Z(M)$ .

By Lemma 2.8,  $\{ r(a, b) \le w \le a, b \} = 0$  for all  $a, b, w \in U$  and  $r, \le x \le \Gamma$ .

Let  $a, b \in U \cap S_{ar}(M)$ . Since  $\dagger 1(U) = U$ , so  $\dagger 1[a, b]_r = [a, b]_r$ , as  $[a, b]_r \in U$ . If  $\dagger 1(b) = -b$  and  $\dagger 1(a) = -a$ , then

 $\dagger 1([a, b]_r) = \dagger 1(arb - bra) = \dagger 1(b)r \dagger 1(a) - \dagger 1(a)r \dagger 1(b) = -bra + arb = [a, b]_r.$ 

Also, if  $\dagger 1(b) = b$  and  $\dagger 1(a) = -a$ , then  $\dagger 1([a, b]_{r}) = [a, b]_{r}$ . Therefore,

 $\{r(a, b) \le w \le [a, b]_r = \{r(a, b) \le w \le 1^+ 1 [a, b]_r\} = 0.$ 

Applying Lemma 2.9 in the above relation,

 $\{{}_{\mathsf{r}}(a,b)=0 \text{ or } [a,b]_{\mathsf{r}}=0, \text{ for all } a,b\in U\cap S_{a\mathsf{r}}(M).$ 

Let  $I_a = \{b \in U : \{ r(a, b) = 0 \}$  and  $J_a = \{b \in U : [a, b]_r = 0 \}$ . Then  $I_a$  and  $J_a$  are additive subgroups of U such that  $I_a \cup J_a = U$ . Then by Brauer's trick  $I_a = U$  or  $J_a = U$ .

Using the similar argument,  $U = \{a \in U : U = I_a\}$  or  $U = \{a \in U : U = J_a\}$ .

If  $U = \{a \in U : U = J_a\}$  then  $[a, b]_{\alpha} = 0$  which yields that  $U \subseteq Z(M)$ , by Lemma 2.5. Which is a contradiction to the fact that  $U \not\subseteq Z(M)$ . So  $U = \{a \in U : U = I_a\}$  and hence  $\{ {}_{\Gamma}(a, b) = 0, \text{ for all } a, b \in U \cap S_{a\Gamma}(M).$  This implies that

$$d(arb) = d(a)rb + arb(b), \ \forall \ a, b \in U \cap S_{ar}(M).$$

$$\tag{2}$$

Now let  $u, v \in U$ . Define  $u_1 = u + \pm 11(u), u_2 = u - \pm 11(u), v_1 = v + \pm 11(v), v_2$ 

$$= v - \dagger 11(v).$$

Then  $u_1, u_2, v_1, v_2 \cap S_{ar}(M)$  and  $2u = u_1 + u_2, 2v = v_1 + v_2$ .

Therefore, in view of (2)

 $d(2uxl_2v) = d(u_1xl_v + u_1xl_v + u_2xl_v + u_2xl_v)$ 

$$= d(u_1)Xlv_1 + u_1Xl(v_1) + d(u_1)Xlv_2 + u_1Xld(v_2) + d(u_2)Xlv_1 + u_2Xld(v_1) + d(u_1)Xlv_2 + u_2Xld(v_2)$$

 $= (d(u_1) + d(u_2))X Iv_1 + (u_1 + u_2)X Id(v_1) + (d(u_1) + d(u_2))X Iv_2 + (u_1 + u_2)X Id(v_2)$ 

$$= d(u_1 + u_2) X I v_1 + 2u X I d(v_1) + d(u_1 + u_2) X I v_2 + 2u X I d(v_2)$$

 $= d(2u)x1v_1 + 2ux1d(v_1) + d(2u)x1v_2 + 2ux1d(v_2)$ 

$$= 2d(u) \times 1(v_1 + v_2) + 2u \times 1d(v_1 + v_2)$$

- = 2d(u)x12v + 2ux1d(2v)
- $= 4d(u)\mathbf{x}\mathbf{1}v + 4u\mathbf{x}\mathbf{1}d(v).$

Thus  $4d(ux_1v) = 4(d(u)x_1v + ux_1d(v))$ .

Since *M* is 2-torsion free, so d(ux|v) = d(u)x|v + ux|d(v).

If *U* is a commutative †1-Lie ideal of *M*, then by Lemma 2.5,  $U \subseteq Z(M)$ .

Therefore, using 2-torsion freeness of M and in view of the Lemma 2.1(i)

 $d(uX1v) = d(u)X1v + uX1d(v) \forall u, v \in U \text{ and } X1 \in \Gamma.$ 

The following corollary is an immediate consequence of the above theorem.

**Corollary 2.11.** If *M* is a 2-torsion free  $\uparrow$ 1-prime  $\Gamma$ -ring, then every Jordan derivation of *M* is a derivation of *M*.

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